

# TraxInterface<sup>4</sup>

## TraxBus INTERFACE CONVERTER

TraxBus™ is a dedicated fieldbus specifically designed to operate in very harsh environments where electrical noise generated by ignition transformers makes very difficult to operate for any standard physical layer. TraxInterface<sup>4</sup> is an active interface converter from TraxBus™ to the following standard physical layers:

- EIA-RS232
- EIA-RS485

TraxInterface<sup>4</sup> can drive up to 250 remote peripherals operating in two different modes:

- Transparent
- Modbus® ASCII / RTU

An additional service port is available for monitoring and configuration.

A complete galvanic isolation is provided between local interfaces to fieldbus and power supply.



### SAFETY INFORMATION

Read and understand this manual before installing, operating, or servicing this unit. This unit must be installed according to this manual and local regulations. The drawings may show units without covers or safety shields to illustrate details. Disconnect power supply and follow all usual safety precautions before carrying out any operation on the device. Be sure to reinstall covers or shields before operating any devices.

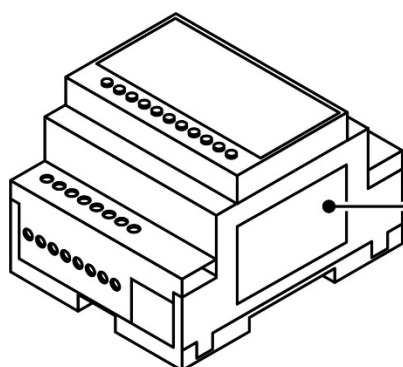
The device is not user serviceable, a faulty device must be put out of order and sent back for servicing.

CONTRIVE manufactures products used as components in a wide variety of industrial systems and equipment. The selection and application of products remain the responsibility of the equipment manufacturer or end user.

CONTRIVE accepts no responsibility for the way its products are incorporated into the final system design. All systems or equipment designed to incorporate a product manufactured by CONTRIVE must be supplied to the end user with appropriate warnings and instructions as to the safe use and operation of that part.

Any warnings provided by CONTRIVE must be promptly provided to the end user.

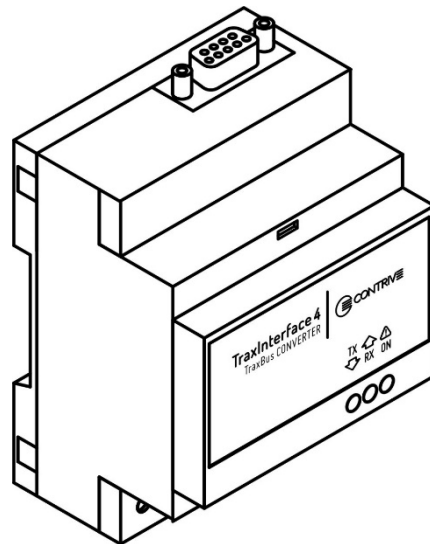
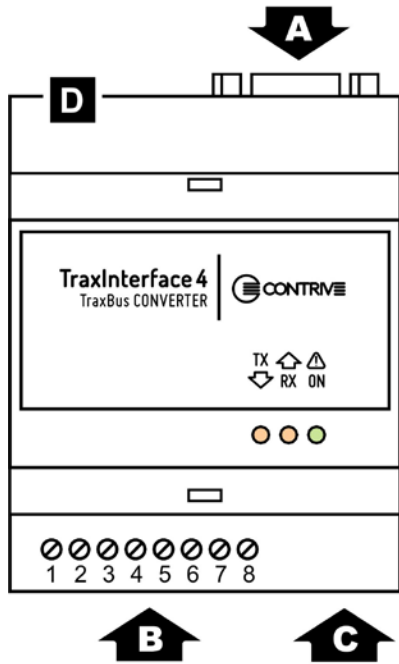
CONTRIVE guarantees for two years from the date of manufacture of its product to replace, or, at its option, to repair any product or part thereof (except fuses and with some limitations for tubes and photocells) which is found defective in material or workmanship or which otherwise fails to conform to the description of its sales order. CONTRIVE makes no warranty of merchantability or any other warranty express or implied. CONTRIVE assumes no liability for any personal injury, property damage, losses, or claims arising from misapplication of its products.



### RECEIVING

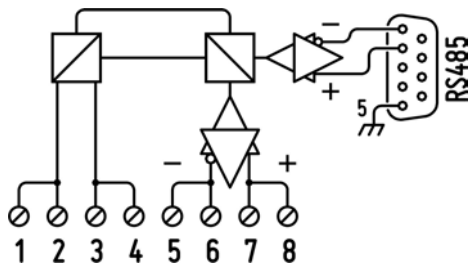
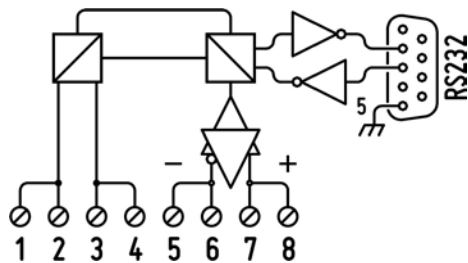
Please perform the following tasks after receiving the TraxInterface<sup>4</sup>:

- Inspect the unit for damage. If the unit appears damaged upon receipt, contact the shipper immediately.
- Verify receipt of the correct unit by checking the label on the right side of the unit.
- If you have received the wrong model or the device does not function properly, contact your supplier.



- MAIN PORT SubD9 FEMALE **A**
- POWER SUPPLY AND BUS TERMINALS **B**
- SERVICE PORT RJ45 **C**
- POWER SUPPLY FUSE REMOVE TOP COVER **D**

- TraxBus™ TRANSMITTED DATA INDICATOR
- TraxBus™ RECEIVED DATA INDICATOR
- POWER ON
- BLINKING ON ModBus® ERROR



## WIRING DIAGRAM

|   |                    |                              |
|---|--------------------|------------------------------|
| 1 | POWER SUPPLY       | (AC/DC POLARITY INDEPENDENT) |
| 2 | POWER SUPPLY       | (AC/DC POLARITY INDEPENDENT) |
| 3 | POWER SUPPLY       | (AC/DC POLARITY INDEPENDENT) |
| 4 | POWER SUPPLY       | (AC/DC POLARITY INDEPENDENT) |
| 5 | TRAXBUS – NEGATIVE |                              |
| 6 | TRAXBUS – NEGATIVE |                              |
| 7 | TRAXBUS – POSITIVE |                              |
| 8 | TRAXBUS – POSITIVE |                              |

| RS232        |                  | RS485        |                  |
|--------------|------------------|--------------|------------------|
| SubD9 FEMALE |                  | SubD9 FEMALE |                  |
| 2            | Tx DATA OUTPUT   | 1            | Tx/Rx NEGATIVE   |
| 3            | Rx DATA INPUT    | 2            | Tx/Rx POSITIVE   |
| 5            | SG SIGNAL GROUND | 5            | SG SIGNAL GROUND |

USE POWER, SIGNAL AND CONTROL CABLE SUITABLE FOR THE TYPE OF OPERATION AND COMPLYING WITH ALL REGULATIONS DO NOT ROUTE FIELD BUS CABLE TOGETHER WITH FREQUENCY CONVERTER CABLES OR CABLES EMITTING STRONG FIELDS ALL ELECTRONIC SYSTEMS MUST BE SUPPLIED BY A DEDICATED TRANSFORMER IN A TN-S EARTHING SYSTEM

### EIA-RS485

THE LINE MUST BE PROPERLY BIASED TO GUARANTEE THE MINIMUM DIFFERENTIAL VOLTAGE OF 200 mV ACROSS INPUTS. PROVIDE BIASING RESISTORS IF REQUIRED. NO TERMINATION RESISTOR IS PROVIDED.

## TraxBus™ NETWORKS

TraxBus™ is an industrial network system for distributed control using a multi-drop wire pair: digital communication enables improved control capability, which can improve product yields. Near real-time operation is possible, despite the relatively low speed, thanks to an efficient protocol.

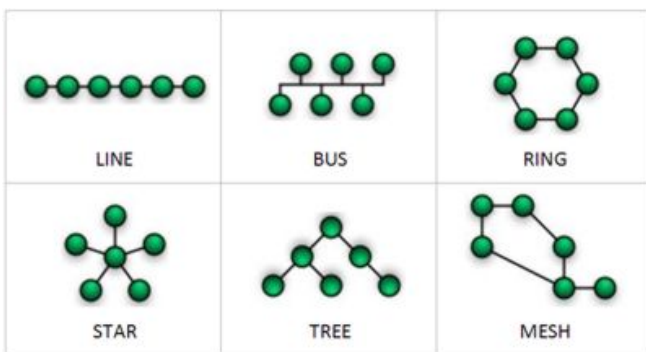
TraxBus™ features high electromagnetic noise immunity and great wiring simplicity, also using busbar trunkets: possible application are in hostile industrial environments where other standard networks doesn't work.

Live connection and disconnection – while the communication is running – are allowed, though a short break in the data flow may result from this operation.

A short-circuit on the TraxBus™ while the unit is transmitting can damage the TraxInterface<sup>4</sup>, a limited time short-circuit while the unit is in idle mode (receiving) is tolerated.

Specific set of commands available for each device equipped with TraxBus™ interface (see detailed information on respective device technical literature).

### TOPOLOGY



TraxBus™ lines can be wired in any form: star, ring, line or mixed but signal line must be wired separately from power lines. Do not use shielded cables.

Do not use multicore cables or limit the usage to short stubs.

Use conventional single wires or busbar trunkets to interconnect all peripherals.

If some shielding is absolutely necessary it is always possible to put twisted pairs in a conduit or grounded metal tube, without packing too many conductors together.

Line capacitance and resistance are important factors.

|                      |                           |
|----------------------|---------------------------|
| OVERALL BUS CAPACITY | 100 nF MAXIMUM            |
| LOOP RESISTANCE      | 60 Ω MAXIMUM              |
| CORE CROSS-SECTION   | 1 mm <sup>2</sup> MINIMUM |

Excessive resistance will cancel data flow from MASTER to peripherals, while excessive capacitance will cancel data flow from peripherals to MASTER.

### USEFUL INFORMATION

- Each TraxInterface<sup>4</sup> can drive up to 250 physical units. Network topology, cables characteristic and other environmental conditions could reduce the number of driven units.
- TraxBus™ is a master/slave system, only 1 master is allowed. The master can drive one or more TraxInterface<sup>4</sup> (using EIA-RS485 multidrop version).
- Additional overvoltage protections on both power supply and data lines must be provided when TraxBus™ is exposed to severe EMC condition.
- The power supply current depends on the number of remote units, as a general rule consider 300 mA + 10 mA per each connected peripheral (e.g.: having 200 units connected on a single bus the external power supply must be capable to deliver 300 + (10\*200) = 2300 mA @ 24Vac).
- Ensure that specified environmental conditions in "Technical data" are complied and make sure there is adequate ventilation around the unit.
- This product is not subject to WEEE Directive 2002/96/EC or relevant national laws. The product must be disposed of at a specialist recycling facility. Do not use municipal garbage collection points. According to the WEEE Directive 2002/96/EC, only products used in private applications may be disposed of at municipal garbage facilities. If it is not possible to dispose of device properly, CONTRIVE can accept and dispose of returns for a fee.

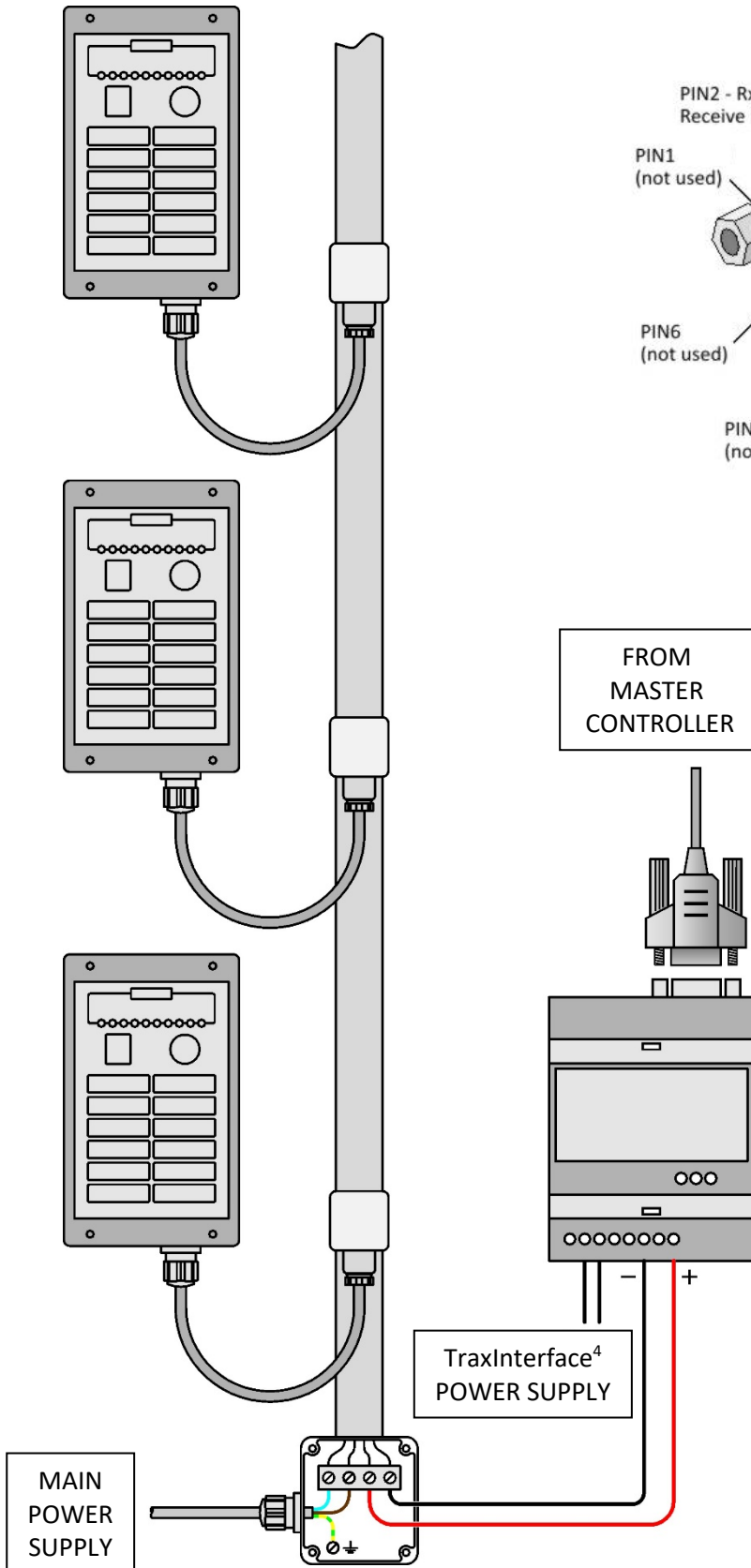
## MAIN PORT RS232

EIA-RS232 interface is a point-to-point connection of two communication devices.

EIA-RS232 is the easiest way to implement TraxBus™ when the number of remote peripherals and the system architecture does not require more than 1 TraxBus™ line.

In the figure below, a single TraxInterface<sup>4</sup> is driving several units deployed on a busbar trunket used for both the main power supply and the communication bus. This solution can simplify the installation and maintenance.

Since the stubs from the units to the busbar socket are made using multi-core cable (usually phase, neutral, ground, communication positive and negative) it is very important to keep those cables as short as possible.



A single master controller is connected to SubD 9 female socket.

The cable coming from the master DTE (Data Terminal Equipment) must be terminated with a SubD male socket.

TraxInterface<sup>4</sup> is Data Communication Equipment (DCE).

Only shielded cables have to be used, required signals are RxD, TxD and GND. No termination resistors are required.

A maximum cable capacitance of 2500 pF is allowed for a RS232 connection (EIA-232). For cables of such capacitance the following maximum lengths are allowed (depending on the baud rate).

| MAX BAUD RATE | MAX LENGTH |
|---------------|------------|
| 19200         | 15 m       |
| 57600         | 5 m        |
| 115200        | 2 m        |

Use ultra low capacitance cable if higher lengths are required.

## MAIN PORT RS485

EIA-RS485 operates in push-pull action over two lines, allowing the connection of up to 32 transceivers, thus can be used to drive one or more TraxBus™ lines.

The bus cable must be a shielded twisted pair cable where the shield should be connected at both ends with large contact areas to the potential equalization system. At higher baud rates the bus requires a termination resistor on each end of approximately the amount of the characteristic wave impedance of the cable, which usually amounts to a value between 120 Ω and 220 Ω.

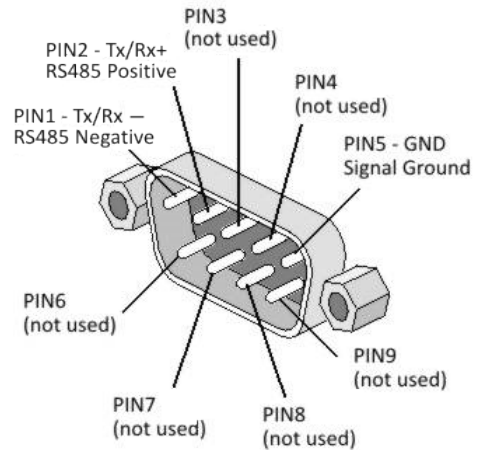
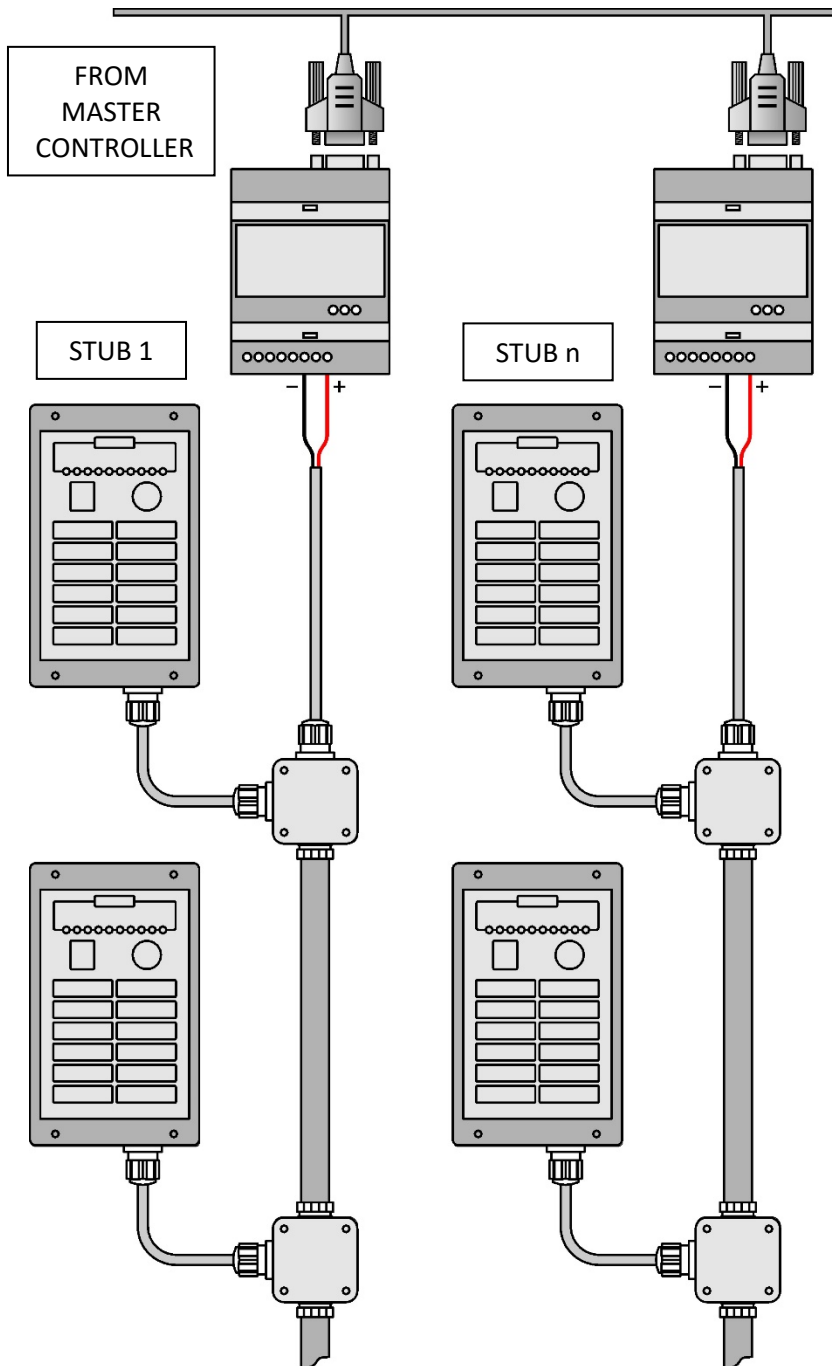
Optional pull-up and pull-down (biasing) resistors should have a value of 390 Ω up to 650 Ω.

Some master controller already includes biasing resistors.

Cabling is an important factor of the reliable operation. It is mandatory to use shielded twisted-pair cables.

| PARAMETER   | VALUE        |
|-------------|--------------|
| IMPEDANCE   | 150 Ω ± 15 Ω |
| CAPACITANCE | < 30 pF/m    |
| RESISTANCE  | 110 Ω/km     |
| WIRE GAUGE  | 0.64 mm      |

Total line must not exceed 1200 m and length of each branch derived from main line should be less than 1.5 m.



### Do I really need termination resistor?

Terminations increase complexity and can potentially load down drivers, we recommend only using termination if it is required. No more than 2 termination resistors should be used, one at each end of transmission line.

Line termination are not needed if the duration of a single bit transmitted is greater at least 10 times the time that the signal takes to travel down the line.

Assuming 1200 m length and 9600 bit/s:

$$BitTx = \frac{1}{\text{baud rate}} = \frac{1}{9600} = 105 \mu\text{s approx}$$

$$tt = \frac{1}{0.66 c} \cdot l = \frac{1}{0.66 \cdot 299\,792\,458} \cdot 1200 = 6\mu\text{s approx}$$

*BitTx* = duration of a single bit transmitted

*tt* = time that the signal takes to travel down the line termination

*l* = network length

*c* = speed of light (Propagation speed in an electrical cable is about 66% the speed of light)

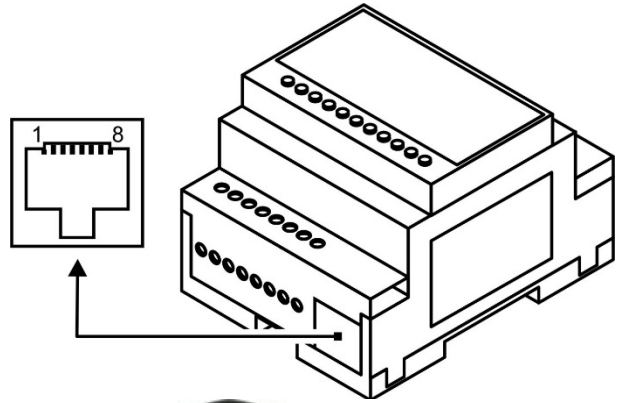
No termination required, since it is verified that:  $BitTx > 10 \cdot tt$

## SERVICE PORT RS232 / EXPANSION

Custom RJ45 modular jack includes RxD, TxD and GND signals of Service Port, useful for configuration, commissioning and troubleshooting.

The same connector provides the link signal to expansion devices like TCU6, a preconfigured remote control and supervisor for 6 burner or zones of burners.

Specific cables are available to convert RJ45 socket to standard connectors and interfaces:



2505.00.03 Mobi.Link USB



2505.00.01 Mobi.Link RS232

Service port operates in 3 different modes, type the command to select:

|      |                           |                          |
|------|---------------------------|--------------------------|
| TRON | >Trace ON                 | Enter TRACE Mode         |
| TRSP | >Local transparent mode   | Enter LOCAL Mode         |
| CNFG | >Local configuration mode | Enter CONFIGURATION Mode |

### TRACE MODE

All data traffic from master to remotes and vice-versa echoed to service port, allowing inspection of bus activity. Commands accepted while in Trace Mode:

|       |            |                 |
|-------|------------|-----------------|
| TROFF | >Trace OFF | Exit Trace mode |
|-------|------------|-----------------|

### LOCAL MODE

Overtakes MAIN PORT, data traffic is redirected to service port ignoring data coming from main port, useful for commissioning and troubleshooting.

Commands accepted while in Local Mode:

|      |     |                 |
|------|-----|-----------------|
| EXIT | >OK | Exit Local mode |
|------|-----|-----------------|

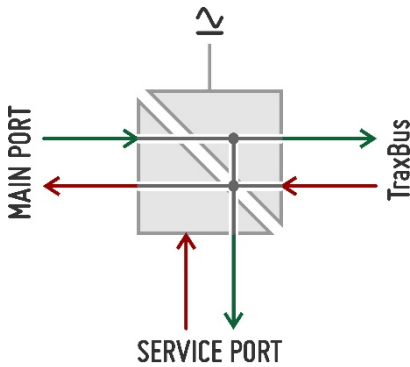
### CONFIGURATION MODE

Normal activity is suspended. TraxInterface<sup>4</sup> can be configured from Service Port by means of specific commands:

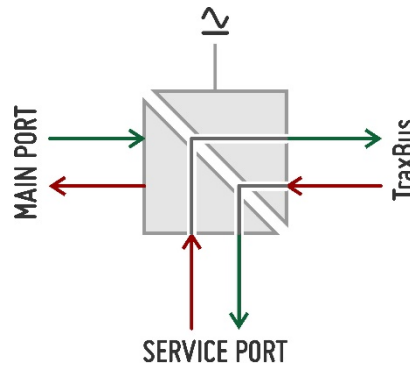
|         |               |  |
|---------|---------------|--|
| EXIT    | >OK           | Exit Configuration mode  |
| help    |               | List of available commands   |
| MODE=T  | >Transparent  | Data transferred from Main Port to remotes and vice-versa                                      |
| MODE=A  | >Modbus ASCII | Main port operates Modbus <sup>®</sup> ASCII protocol  |
| MODE=R  | >Modbus RTU   | Main port operates Modbus <sup>®</sup> RTU protocol  |
| MODE=?  | >MODE=...     | Returns current Main port operating mode   |
| PRM={x} | >BPM={z}      | Set Framing for Main port<br>{z} = N (8N2) E (8E1) O (8O1)                                     |
| BRM={x} | >BRM={x}      | Set Baud rate for Main port  |
| BRM=?   | >BRM={x}      | Returns current baud rate of Main port<br>{x} = 4800 9600 19200 38400 57600 115200             |
| BRS={y} | >BRM={y}      | Set Baud rate for Slave port (TraxBus <sup>™</sup> )   |
| BRS=?   | >BRM={y}      | Returns current baud rate of Slave port (TraxBus <sup>™</sup> )<br>{y} = 4800 9600 19200 38400 |

**Use free software utility Q|tool for easy configuration and management of TraxInterface<sup>4</sup>**

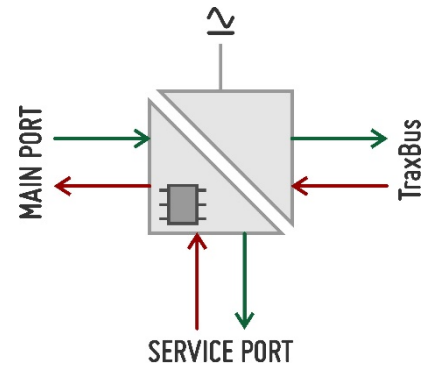
**TRACE MODE §**  
 MAIN RX → TRAXBUS TX  
 MAIN TX ← TRAXBUS RX  
 SERVICE RX – DISABLED  
 SERVICE TX ← TRAXBUS TX & RX



**LOCAL MODE**  
 MAIN RX – DISABLED  
 MAIN TX – DISABLED  
 SERVICE RX → TRAXBUS TX  
 SERVICE TX ← TRAXBUS RX



**CONFIGURATION MODE**  
 MAIN & TRAXBUS RX – DISABLED  
 MAIN & TRAXBUS TX – DISABLED  
 SERVICE RX → INTERFACE SETUP  
 SERVICE TX ← INTERFACE SETUP

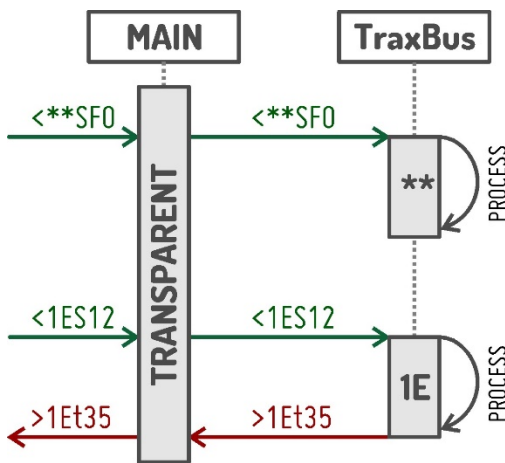


§ A LITTLE DELAY IS INTRODUCED TO CYCLIC COMMUNICATION WHILE IN TRACE MODE

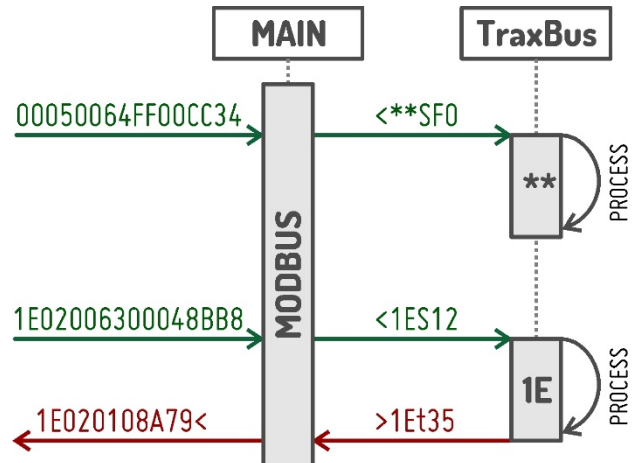
### CYCLIC COMMUNICATION

TraxInterface<sup>4</sup> receives data from Main Port at specified baud rate and send data to TraxBus™ at specified baud rate and protocol, without buffering. This means that the overall response time for each communication is affected by the lowest baud rate among Main Port and TraxBus™, adding the process time of the addressed peripheral.

**TRANSPARENT MODE**  
 MAIN RX {TRAX} → TRAXBUS TX {TRAX}  
 MAIN TX {TRAX} ← TRAXBUS RX {TRAX}



**MODBUS® MODE**  
 MAIN RX {MODBUS} → TRAXBUS TX {TRAX}  
 MAIN TX {MODBUS} ← TRAXBUS RX {TRAX}



Master supervisor sends commands to TraxInterface<sup>4</sup> using the TRAX protocol made by simple ASCII commands and described in each device literature or using the Modbus® protocol as described later in this document. In the schema above, the first command is broadcast, it is received and processed by all networked units but there is no answer (to prevent collision due to concurrent response). The second command, addressed to specific peripheral 1E, issued transparently (left) or converted from Modbus® protocol (right) is processed by addressed unit that will return an answer.

### TRANSPARENT MODE

Data received from the Main Port is transferred to TraxBus™ port and vice-versa. Baud rate could be different for Main port and TraxBus™ port, TraxInterface<sup>4</sup> converts the data speed between the two ports. This is the default operating mode.

## MODBUS® MODE

### PERIPHERAL ADDRESS WITHIN A NETWORK

The address field of the message frame contains two characters (in ASCII mode), or 8 binary bits (in RTU Mode). Valid addresses are from 1-247 (00-F7 HEX), corresponding to the address set for each remote peripheral. When the slave responds, it places its own address in this field of its response to let the master know which slave is responding. Address 0 (00 HEX) is reserved for the broadcast address, which all slave devices on a network recognize. Some functions does not support broadcast. A slave device does not issue a response to a broadcast message.

### DATA ADDRESS WITHIN A PERIPHERAL

All data addresses in Modbus® messages are referenced to 0, with the first occurrence of a data item addressed as item number zero.

Further, a function code field already specifies which register group it operates on (i.e. 0x, 1x, 3x, or 4x reference addresses). For example, holding register 40001 is addressed as register 0000 in the data address field of the message. The function code that operates on this register specifies a "holding register" operation and the "4xxxx" reference group is implied.

Thus, holding register 40108 is actually addressed as register 006B HEX (107 decimal).

### MODBUS® FUNCTIONS

The table highlights the subset of standard functions used by TraxBus™. When a remote device responds to the master, it uses the function code field to indicate either a normal (error-free) response, or that some kind of error has occurred (exception response).

The number of registers returned in a single answer is limited to 1, the number of coils returned in a single answer is limited to 16.

A valid answer is given if at least one of read coil is valid, in such case the value returned for invalid ones will be 0 (zero).

An error is given when the whole addresses are not valid.

#### Read input status

This command will read the ON/OFF status of discrete or logical inputs in remote units.

Broadcast transmission is not supported.

Note that the leading character 1x reference address is implied by the function code and omitted from the address specified.

This query specifies the starting address and quantity of points to be read. Following the Modbus® specification, the example reads 4 points from the starting address 99 (63 HEX) corresponding to coil 100.

The response message is packed as one input per bit of each data field, the status indicated as 1 for ON (closed, active) and 0 for OFF (open, inactive). The LSB of the first data byte corresponds to the status of the input addressed in the query, the other inputs follow sequentially, moving toward the high end of the byte.

Unused bits of the data bit will be set to 0 (zero).

|        |   |   |   |   |    |     |     |     |
|--------|---|---|---|---|----|-----|-----|-----|
| BYNARY | 0 | 0 | 0 | 0 | 1  | 0   | 0   | 0   |
| HEX    | 0 |   |   |   | 8  |     |     |     |
| INPUTS | - | - | - | - | ON | OFF | OFF | OFF |

| CODE | FUNCTION                   | REFERENCE |
|------|----------------------------|-----------|
| 02   | READ INPUT STATUS          | 1xxxx     |
| 05   | FORCE SINGLE COIL          | 0xxxx     |
| 04   | READ INPUT REGISTER        | 3xxxx     |
| 06   | PRESET SINGLE REGISTER     | 4xxxx     |
| 43   | READ DEVICE IDENTIFICATION |           |

EXAMPLE                    1E 02 0063 0004 8BB8

| QUERY FIELD             | VALUE | HEX  |
|-------------------------|-------|------|
| SLAVE ADDRESS           | 30    | 1E   |
| FUNCTION CODE           | 2     | 02   |
| STARTING ADDRESS (HIGH) | 99    | 00   |
| STARTING ADDRESS (LOW)  |       | 63   |
| NUMBER OF POINTS (HIGH) | 4     | 00   |
| NUMBER OF POINTS (LOW)  |       | 04   |
| CRC/LRC                 |       | 8BB8 |

This example asks for LOCKOUT, MANUAL SHUTDOWN, REMOTE HALT, THERMOSTAT HALT of QBK whose address is 1E (reading coil 100 to 103).

| RESPONSE FIELD | VALUE | HEX  |
|----------------|-------|------|
| SLAVE ADDRESS  | 30    | 1E   |
| FUNCTION CODE  | 2     | 02   |
| BYTE COUNT     | 1     | 01   |
| DATA COILS     | 8     | 08   |
| CRC/LRC        |       | A79A |



### Read input register

This command will read the binary content of input or logical registers in remote units.

Broadcast transmission is not supported.

Note that the leading character 3x reference address is implied by the function code and omitted from the address specified.

This query specifies the starting address and quantity of points to be read that is limited to 1 register per query. Following the Modbus® specification, the example reads 1 register from starting address 100 (64 HEX) corresponding to register 101 (QBK flame signal = 18 µA).

The response message is the current value of register. An error is returned reading more than 1 register at a time.

### Force single coil

Forces a single coil to either ON or OFF. With broadcast transmission it forces the same coil in all networked units.

This query specifies the coil reference address to be forced and the state to force it to.

The ON/OFF state is indicated via a constant in the query field. A value of FF00HEX forces the coil to be turned ON and 0000HEX forces the coil to be turned OFF, all other values are invalid and will not affect the coil.

Note that the leading character 0x reference address is implied by the function code and omitted from the address specified. The starting coil address 101 (65 HEX).

The response message is simply an echo (copy) of the query. No response is returned to broadcast queries.

### Preset single register

This command presets a single holding register (4x reference addresses) to a specific value.

When broadcast, the function presets the same register reference in all networked units.

This query specifies the register reference address to be preset and the preset value.

The response message is simply an echo (copy) of the query. No response is returned to broadcast queries.

EXAMPLE            1E 04 0064 0001 727A

| QUERY FIELD             | VALUE | HEX  |
|-------------------------|-------|------|
| SLAVE ADDRESS           | 30    | 1E   |
| FUNCTION CODE           | 4     | 04   |
| STARTING ADDRESS (HIGH) | 100   | 00   |
| STARTING ADDRESS (LOW)  |       | 64   |
| NUMBER OF POINTS (HIGH) | 1     | 00   |
| NUMBER OF POINTS (LOW)  |       | 01   |
| CRC/LRC                 |       | 727A |

This example asks for FLAME SIGNAL of QBK whose address is 1E (reading register 101).

| RESPONSE FIELD | VALUE | HEX  |
|----------------|-------|------|
| SLAVE ADDRESS  | 30    | 1E   |
| FUNCTION CODE  | 4     | 04   |
| BYTE COUNT     | 1     | 01   |
| DATA (HIGH)    | 18    | 00   |
| DATA (LOW)     |       | 12   |
| CRC/LRC        |       | 5CFF |

EXAMPLE            1E 05 0064 FF00 CF8A

| QUERY FIELD             | VALUE | HEX  |
|-------------------------|-------|------|
| SLAVE ADDRESS           | 30    | 1E   |
| FUNCTION CODE           | 5     | 05   |
| STARTING ADDRESS (HIGH) | 100   | 00   |
| STARTING ADDRESS (LOW)  |       | 64   |
| FORCE DATA (HIGH)       | 255   | FF   |
| FORCE DATA (LOW)        | 0     | 00   |
| CRC/LRC                 |       | CF8A |

This example send a RUN command to QBK whose address is 1E (turning on coil 101).

EXAMPLE            01 06 00C8 03E8 088A

| QUERY FIELD             | VALUE | HEX  |
|-------------------------|-------|------|
| SLAVE ADDRESS           | 1     | 01   |
| FUNCTION CODE           | 6     | 06   |
| STARTING ADDRESS (HIGH) | 200   | 00   |
| STARTING ADDRESS (LOW)  |       | C8   |
| PRESET DATA (HIGH)      | 1000  | 03   |
| PRESET DATA (LOW)       |       | E8   |
| CRC/LRC                 |       | 088A |

This example preset to 1000 the SETPOINT TEMPERAURE of Q|TC whose address is A0 (writing register 201).

## MODBUS® EXCEPTIONS

In a normal response the most significant bit (MSB) of the returned function code equals to 0 (zero).

In an exception response the most significant bit (MSB) of the returned function code equals to 1, exactly 80 HEX higher than normal value. The exception code is specified in the data field. This is used by the master's application to recognize an exception response and to direct an examination of the data field for the applicable exception code:

| CODE | EXCEPTION            | DESCRIPTION   |
|------|----------------------|---|
| 01   | ILLEGAL FUNCTION     | The function code received in the query is not allowed or invalid           |
| 02   | ILLEGAL DATA ADDRESS | The data address received in the query is not allowable or is invalid       |
| 03   | ILLEGAL DATA VALUE   | A value contained in the query data field is not an allowable or is invalid |
| 04   | SLAVE DEVICE FAILURE | An unrecoverable error occurred while attempting to perform the request     |
| 07   | NEGATIVE ACKNOWLEDGE | The slave cannot perform the program function received in the query         |

The master's application program must handle the exception response.

It may choose to post subsequent retries of the original message, it may try sending a diagnostic query, or it may simply notify the operator of the exception error.

## CONVERSION FROM MODBUS® TO TraxBus™

TraxInterface<sup>4</sup> converts Modbus® commands to equivalent TraxBus™ commands and TraxBus™ answers to equivalent Modbus® answers. This activity is based on a predefined conversion table supporting some specific remote units. Only commands received from the Main port that have a match are converted and sent to peripherals. There is no memory map within TraxInterface<sup>4</sup>.

### Q|TC – Remote thermocouple

Read input status returns coils representing specific status of remote unit:

| COIL   | STATUS   |
|--------|--|
| 1 0200 | Returns the status of RELAY OUTPUT (equivalent to status 1   0). |
| 1 0201 | Returns the ERROR for thermocouple not connected or broken.      |
| 1 0202 | Returns the ERROR for input signal over/undervoltage.            |
| 1 0203 | Returns the ERROR for thermocouple input out of range.           |
| 1 0204 | Returns the ERROR for cold junction temperature out of range.    |

Force single coil to control specific function of remote unit:

| COIL   | ACTION  |
|--------|---|
| 0 0200 | Behavior similar to a switch, set 1 to switch RELAY on and set 0 to switch RELAY off. |

Read input register is converted to the corresponding command for Q|TC:

| REGISTER | STATUS  |
|----------|---|
| 3 0200   | Returns current setpoint, range -210...1820 [°C] (equivalent to command S). #               |
| 3 0201   | Returns current HIGH threshold, range -210...1820 [°C] (equivalent to command U). #         |
| 3 0202   | Returns current LOW threshold, range -210...1820 [°C] (equivalent to command D). #          |
| 3 0203   | Returns thermocouple temperature, range -210...1820 [°C] (equivalent to command T). #       |
| 3 0204   | Returns current cold junction temperature, range -25...85 [°C] (equivalent to command J). # |

Preset single register is converted to the corresponding command for Q|TC:

| REGISTER | ACTION  |
|----------|---|
| 4 0201   | Setpoint temperature, range -210...1820 [°C]. # |

# ANALOG VALUES ARE 16 BIT SIGNED

## QBK – Burner Control Unit

Read input status returns coils representing specific status of burner controller:

| COIL   | STATUS   |
|--------|--|
| 1 0100 | Returns 1 when QBK is in LOCKOUT or FAILURE (equivalent to status S).        |
| 1 0101 | Returns 1 when QBK is in MANUAL SHUTDOWN (equivalent to status O).           |
| 1 0102 | Returns 1 when QBK is in REMOTE HALT (equivalent to status H).               |
| 1 0103 | Returns 1 when QBK is waiting for local THERMOSTAT (equivalent to status t). |
| 1 0104 | Returns 1 when QBK is waiting for AIR PRESSURE (equivalent to status A).     |
| 1 0105 | Returns 1 during PREPURGE (equivalent to status P).                          |
| 1 0106 | Returns 1 during IGNITION (equivalent to status I).                          |
| 1 0107 | Returns 1 when PILOT burner is ON (equivalent to status 2).                  |
| 1 0108 | Returns 1 when both PILOT and MAIN burner are ON (equivalent to status 3).   |
| 1 0109 | Returns 1 when MAIN burner is ON (equivalent to status 4).                   |
| 1 0110 | Returns 1 during POSTCOMBUSTION (equivalent to status Y).                    |
| 1 0111 | Returns 1 during POSTPURGE (equivalent to status W).                         |
| 1 0112 | Returns 1 when BURNER is ON (equivalent to status P 1 2 3 4).                |
| 1 0113 | Returns 1 when BURNER is OFF (equivalent to status 0 H t).                   |

Force single coil to control specific function of remote burner controller:

| COIL   | ACTION  |
|--------|---|
| 0 0100 | Behavior similar to a remote push button, set 1 for a while to RESET from lockout.                                      |
| 0 0101 | Behavior similar to thermostat, set 1 to RUN the burner and set 0 to HALT the burner.                                   |
| 0 0102 | Behavior similar to main burner thermostat, set 1 to RUN 2 <sup>nd</sup> stage and set 0 to HALT 2 <sup>nd</sup> stage. |
| 0 0103 | Behavior similar to a switch, set 1 to switch on AIR output and set 0 to switch off AIR output.                         |

Read input register is converted to the corresponding command for QBK:

| REGISTER | STATUS   |
|----------|--|
| 3 0100   | Cumulative status:   |
|          | BIT 0 Same as coil 10100 – Lockout   |
|          | BIT 1 Same as coil 10101 – Manual Shutdown   |
|          | BIT 2 Same as coil 10102 – Remote Halt   |
|          | BIT 3 Same as coil 10103 – Thermostat Halt   |
|          | BIT 4 Same as coil 10104 – Air pressure waiting  |
|          | BIT 5 Same as coil 10105 – Prepurge  |
|          | BIT 6 Same as coil 10106 – Ignition  |
|          | BIT 7 Same as coil 10107 – Pilot on  |
|          | BIT 8 Same as coil 10108 – Pilot & Main on   |
|          | BIT 9 Same as coil 10109 – Main on   |
|          | BIT 10 Same as coil 10110 – Postcombustion   |
|          | BIT 11 Same as coil 10111 – Postpurge  |
|          | BIT 12 Same as coil 10112 – Buner on   |
|          | BIT 13 Same as coil 10113 – Burner off   |
|          | ... All other bits not used  |
| 3 0101   | Current flame signal, analog value in the range 0 to 26 µA.                                      |
| 3 0110   | Current air damper position from 0 to 99% of working range (between MIN / MAX limit switches). § |
| 3 0111   | Current air damper overdrive from 0 to 99 seconds below the MIN limit switch. §                  |

Preset single register is converted to the corresponding command for QBK:

| REGISTER | ACTION   |
|----------|--|
| 4 0110   | Air damper position control from 0 to 99% of working range (between MIN and MAX limit switches). § |
| 4 0111   | Air damper overdrive control from 0 to 99 seconds below the MIN limit switch. §                    |

§ REQUIRES Q|SM ADDITIONAL BOARD

## SPAC44 – Remote digital I/O

Read input status returns coils representing specific status of remote unit:

| COIL   | STATUS   |
|--------|--|
| 1 0300 | Returns 1 when SPAC44 is in LOCKOUT (Communication failure). |
| 1 0301 | Returns 1 when SPAC44 input 1 is closed (ON).                |
| 1 0302 | Returns 1 when SPAC44 input 2 is closed (ON).                |
| 1 0303 | Returns 1 when SPAC44 input 3 is closed (ON).                |
| 1 0304 | Returns 1 when SPAC44 input 4 is closed (ON).                |

Force single coil to control specific function of remote burner controller:

| COIL   | ACTION   |
|--------|--|
| 0 0300 | Behavior similar to a remote push button, close for a while to RESET from lockout.       |
| 0 0301 | Behavior similar to a switch, set 1 to switch OUTPUT 1 on and set 0 to switch RELAY off. |
| 0 0302 | Behavior similar to a switch, set 1 to switch OUTPUT 2 on and set 0 to switch RELAY off. |
| 0 0303 | Behavior similar to a switch, set 1 to switch OUTPUT 3 on and set 0 to switch RELAY off. |
| 0 0304 | Behavior similar to a switch, set 1 to switch OUTPUT 4 on and set 0 to switch RELAY off. |
| 0 0311 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on for 1 second.             |
| 0 0312 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on for 1 second.             |
| 0 0313 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on for 1 second.             |
| 0 0314 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on for 1 second.             |
| 0 0321 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on for 2 seconds.            |
| 0 0322 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on for 2 seconds.            |
| 0 0323 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on for 2 seconds.            |
| 0 0324 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on for 2 seconds.            |
| 0 0331 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on for 5 seconds.            |
| 0 0331 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on for 5 seconds.            |
| 0 0332 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on for 5 seconds.            |
| 0 0333 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on for 5 seconds.            |
| 0 0341 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on after 1 second.           |
| 0 0342 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on after 1 second.           |
| 0 0343 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on after 1 second.           |
| 0 0344 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on after 1 second.           |
| 0 0351 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on after 5 seconds.          |
| 0 0352 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on after 5 seconds.          |
| 0 0353 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on after 5 seconds.          |
| 0 0354 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on after 5 seconds.          |
| 0 0361 | Behavior similar to a push button, set 1 to switch OUTPUT 1 on after 10 seconds.         |
| 0 0362 | Behavior similar to a push button, set 1 to switch OUTPUT 2 on after 10 seconds.         |
| 0 0363 | Behavior similar to a push button, set 1 to switch OUTPUT 3 on after 10 seconds.         |
| 0 0364 | Behavior similar to a push button, set 1 to switch OUTPUT 4 on after 10 seconds.         |
| 0 0371 | Behavior similar to a push button, set 1 to switch OUTPUT 1 off after 1 second.          |
| 0 0372 | Behavior similar to a push button, set 1 to switch OUTPUT 2 off after 1 second.          |
| 0 0373 | Behavior similar to a push button, set 1 to switch OUTPUT 3 off after 1 second.          |
| 0 0374 | Behavior similar to a push button, set 1 to switch OUTPUT 4 off after 1 second.          |
| 0 0381 | Behavior similar to a push button, set 1 to switch OUTPUT 1 off after 5 seconds.         |
| 0 0382 | Behavior similar to a push button, set 1 to switch OUTPUT 2 off after 5 seconds.         |
| 0 0383 | Behavior similar to a push button, set 1 to switch OUTPUT 3 off after 5 seconds.         |

- 0 0384 Behavior similar to a push button, set 1 to switch OUTPUT 4 off after 5 seconds.

---

- 0 0391 Behavior similar to a push button, set 1 to switch OUTPUT 1 off after 10 seconds.

---

- 0 0392 Behavior similar to a push button, set 1 to switch OUTPUT 2 off after 10 seconds.

---

- 0 0393 Behavior similar to a push button, set 1 to switch OUTPUT 3 off after 10 seconds.

---

- 0 0394 Behavior similar to a push button, set 1 to switch OUTPUT 4 off after 10 seconds.

---

Read input register is converted to the corresponding command for SPAC44:

**REGISTER STATUS**

|        |                    |       |                              |
|--------|--------------------|-------|------------------------------|
| 3 0300 | Cumulative status: | BIT 0 | Same as coil 10300 – Lockout |
|        |                    | BIT 1 | Same as coil 10301 – Input 1 |
|        |                    | BIT 2 | Same as coil 10302 – Input 2 |
|        |                    | BIT 3 | Same as coil 10303 – Input 4 |
|        |                    | BIT 4 | Same as coil 10303 – Input 4 |
|        |                    | ...   | All other bits not used      |

Preset single register is converted to the corresponding command for SPAC44:

**REGISTER ACTION**

|        |                       |       |                         |        |        |         |         |
|--------|-----------------------|-------|-------------------------|--------|--------|---------|---------|
| 4 0300 | Board initialization: | BIT 0 | Baud rate               | 0      | 0      | 1       | 1       |
|        |                       | BIT 1 | Baud rate               | 0 4800 | 1 9600 | 0 19200 | 1 38400 |
|        |                       | BIT 8 | Timeout                 | 0      | 0      | 1       | 1       |
|        |                       | BIT 9 | Timeout                 | 0 OFF  | 1 8"   | 0 32"   | 1 64"   |
|        |                       | ...   | All other bits not used |        |        |         |         |

BOARD INITIALIZATION IS THE FIRST MANDATORY COMMAND TO SEND TO SPAC44

**OTHER FIELDBUSES**

There are several gateways providing seamless conversion between Modbus® RTU and other industry standard fieldbuses, we tested and recommend netTAP 100 manufactured by Hilscher GSmbH. We can provide pre-configured gateways to following standards on request:

| NT100-DP-RS                             | NT100-RE-RS  | NT100-DN-RS                         | NT100-CO-RS                     |
|---|--|-------------------------------------|---------------------------------|
| PROFIBUS-DP Master<br>PROFIBUS-DP Slave | PROFINET Master<br>PROFINET Slave<br>MODBUS-TCP Master<br>MODBUS-TCP Slave<br>ETHERNET-IP Master<br>ETHERNET-IP Slave<br>SERCOS Master<br>SERCOS Slave | DEVICENET Master<br>DEVICENET Slave | CANOPEN Master<br>CANOPEN Slave |



## TECHNICAL DATA

### POWER SUPPLY

|                   |                                   |
|-------------------|-----------------------------------|
| VOLTAGE           | 24 VAC / 30VDC ±10%               |
| FREQUENCY         | 0 ... 200 Hz                      |
| LINE FUSE         | 3 A QUICKBLOW - 5x20mm            |
| POWER CONSUMPTION | 8 ... 70 VA 1 ... 250 PERIPHERALS |
| POWER DISSIPATION | 3 ... 20 W 1 ... 250 PERIPHERALS  |
| ISOLATION         | 4000 V DC / 1 sec                 |
| TERMINALS         | 2 x 2,5 mm <sup>2</sup> (AWG14)   |

### ENVIRONMENT

|                        |                           |
|------------------------|---------------------------|
| OPERATING TEMPERATURE  | -20 ... 80 °C             |
| STORAGE TEMPERATURE    | -40 ... 85 °C             |
| ENCLOSURE              | POLYCARBONATE UL94-V0     |
| PROTECTION CLASS       | IP20                      |
| RELATIVE HUMIDITY      | 30 ... 90% NON CONDENSING |
| DIMENSIONS (W x H x D) | 71 x 90 x 58 mm           |
| MOUNTING POSITION      | ANY                       |

### TRAXBUS™ INTERFACE

|                            |                                    |
|----------------------------|------------------------------------|
| TYPE                       | ASYNCHRONOUS MULTIDROP HALF DUPLEX |
| PERIPHERALS                | 300 MAX                            |
| BAUD RATE                  | 38400 MAX                          |
| BUS VOLTAGE                | 24 VDC MAX                         |
| BUS CURRENT                | 2,5 A MAX                          |
| ALLOWABLE VOLTAGE DROPOUT  | 3 V MAX                            |
| ALLOWABLE LINE CAPACITANCE | 100 nF MAX                         |
| ISOLATION                  | 3750 V RMS                         |
| TERMINALS                  | 4 x 2,5 mm <sup>2</sup> (AWG14)    |

### EIA RS-232

|              |  |
|--------------|--|
| DATA FORMAT  | SERIAL ASYNCHRONOUS UART/NRZ                                   |
| DEVICE TYPE  | DCE  |
| PROTOCOLS    | TRANSPARENT, MODBUS ASCII, MODBUS RTU                          |
| BAUD RATE    | 4800, 9600, 19200, 38400, 57600, 115200                        |
| DATA FRAMING | 8N1   8N2 TRANSPARENT<br>8N2   8E1   8O1 MODBUS (ASCII OR RTU) |

### EIA RS-485

|                 |  |
|-----------------|--|
| MULTIDROP UNITS | 32 MAX   |
| LINE LENGTH     | 1200 m MAX   |
| PROTOCOLS       | TRANSPARENT, MODBUS ASCII, MODBUS RTU                          |
| BAUD RATE       | 4800, 9600, 19200, 38400, 57600, 115200                        |
| DATA FRAMING    | 8N1   8N2 TRANSPARENT<br>8N2   8E1   8O2 MODBUS (ASCII OR RTU) |

### SERVICE PORT (RS232)

|              |                              |
|--------------|------------------------------|
| DATA FORMAT  | SERIAL ASYNCHRONOUS UART/NRZ |
| BAUD RATE    | 19200                        |
| DATA FRAMING | 8N1                          |

**EIA RS-232** Interface Between Data Terminal Equipment and Data Circuit Terminating Equipment Employing Serial Binary Data Interchange

**EIA RS-485** Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems

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